HD EKO 10 ELEVATOR CONTROL CARD

USER MANUAL

HEDEFSAN

HD EKO 10 I USER MANUAL

PARAMETER LIST			
00	Elevator Type	19	Fire Stop
01	Command Type	20	Park Stop
02	Door Type	21	Return to Park
03	Automatic Door at Floor	22	Busy Time
04	Automatic Door at Park	23	Wait at Stop
05	One Door Full Automatic	24	Door Open Time
06	Special Door Setting	25	Lock Waiting
07	Number of Stops	26	Door Still Open Error
08	Cabin Serial Card	27	Photocell Waiting
09	Phase Protection	28	Fast Cruising
10	Phase Leve	29	Slow Cruising
11	Ptc	30	RP Delay
12	Contact Feedback	31	Plug Delay
13	Position reset	32	Lock Delay
14	Limit Switch	33	Maintenance Time
15	Digital Setting	34	Change Password
16	Display Exit	35	Counter Type
17	Max. Car Call Registration	36	Factory Settings
18	Number of Basement		

TECHNICAL SPECIFICATIONS		
Dimensions Lenght × Width × Hight (mm)	181 × 150 × 22	
Operation Temperature	±0 - +60 °C	
Protection Class	IP20	
Humidity	%95	
Network Control Inputs	3 x 380V, 50Hz, N	
Control Feed Voltage	24 ± 5 Vdc	
Power Usage	Max. 400mA 10W, for 24VDC	
Security Circuit Voltage	230Vac max. For hydraulic elevators in emergency descent 24Vdc	
Control Signal Inputs	24 ± 5 Vdc	
Control Signal Outputs	24 ± 5 Vdc Short circuit protected	

▲ GENERAL FEATURES

- 2-line 16-character LCD display and 4 button keyboard
- RS-485 serial communication for group operation
- RS-485 serial communication for serial system connection with cabin
- Including phase sequential motor protection circuit
- Including in- and output control of 2 automatic doors
- Short circuit protected digital and signal outputs
- Setting of indicator possible via menu: 7-segment and Gray code

UPENING SCREEN

HEDEFSAN HD-EKO Ver_1.9

When you power on, you can view the software version and serial number of the card on the opening screen. After a couple a seconds the screen changes to the MAIN SCREEN.

MAIN SCREEN

Waitin9 for recordin9... D:10 +25.4V

Here it shows the feed voltage and the number of the floor where the elevator is at the present.

ELEVATOR TYPE

00:Lift Type Double Speed

Set your elevator drive type here

One Speed	Choose this setting for single speed roped elevators.	
Double Speed	Choose this setting for double speed roped elevators.	
Roped VVVF	Continous gear (with asynchronous machine) and gearless	
	(with synchronous machine)	

COMMAND TYPE

01:Command Type Simple Command	Set your elevator command type here.
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Simple Command	The cabin and floor buttons are connected parallely. No other expect the one registration is kept in memory.
Mixed Collective	The cabin and floor buttons are connected parallely. Registrations are kept in memory.
Down Collective	The cabin and floor buttons are connected seperately. Cabin registra- tions are collected from both sides. Floor calls are collected when when cabin moves in downward direction.
Full Collective (both ways)	Cabin registrations and the up and down buttons at the floors are connected seperately. Cabin registrations and floor calls are collected in appropriate manner of movement direction.

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DOOR TYPE

02:Door Type Swing Door

Set the open-close signal type for automatic doors here.

Swing Door	Only for elevators that have no automatic door.
Aut. Unlimited	Only used for elevators with automatic unlimited cabin doors.
Aut. limited	Only used for elevators with automatic limited cabin doors.
Full Aut. Unlimited	Only used for elevators with full automatic unlimited cabin doors.
Full Aut. limited	Only used for elevators with full automatic limited cabin doors.



• According to the EN 81-1/2 standarts in states of emergency stop, revision and take back automatic doors must remain stationary

AUTOMATIC DOOR AT FLOOR

03:Aut.Door.At.Floor Closed Standby

Set the open or closed position of the automatic door when waiting at floor.

AUTOMATIC DOOR AT PARK

04: Aut.Door.At.Park Wait closed

Set the open or closed position of the automatic door when waiting at park.

ONE DOOR FULL AUTOMATIC

05:One Door Full Aut. Cancel On elevators with swing doors, set this parameter when there's only one full automatic door.

SPECIAL DOOR SETTING

06:Special Door Setting Floor:10 Door:AB	Set the floor at which you want to open the automatic A and B doors. When floor number is blinking, change the floor number with the UP-DOWN buttons till you come to the floor number you want to change. Press the ENTER button and next you will see the door setting blinking. A-B Determine the door setting again by using the UP-DOWN buttons.
	NUMBER OF STOP
07:Number of Stops D:10	Set the number of stops (maximum 10) here
	CABIN SERIAL CARD
08:Cabin Serial Card 19200 Baud	Set the communication speed between the main controller card and the serial communication card here. Or choose to ignore it
	PHASE PROTECTION
09:Phase Protection Phase Sequence	Set the phase sequence or deactivate the phase here.
Out of Order	Deactivate phase
Phase unsequenced	Activates phase without sequence
Phase sequenced	Activates phase sequenced.
	PHASE LEVEL
10:Phase Level 030	Adjust the phase imbalance here
020 - 060	These are the minimum and maximum phase balance time

	PTC
11:Ptc Active	Choose the PTC motor thermistor input setting.
ACTIVE	Activates it
CANCEL	Deactivates it.
	CONTACT FEEDBACK
12:Contact Feedback Active	Set here the bypassing of the contact feedback error. The controller card does not detect any contactor adhesion when it's cancelled. If it is canceled our company is not responsible.
ACTIVE	Activating the contact feedback error
CANCEL	Bypassing the contact feedback error
	POSITION RESET Even when there's a power blackout the controller card will remem- ber its last position. But in some special cases when the power re-
13:Position Reset Cancel	turns, a position reset may be wanted. In that case the elevator will go until it reaches the 817 limit switch of the bottom floor. When it reaches the bottom floor, the floor counter will reset. For example: with systems that have battery charged rescuers, this parameter can be activated to reset the position.
ACTIVE	Position Reset Activates it.
CANCEL	Position Reset Deactivates it.

REVISION LIMIT SWITCH

14:Rev	/. Lim	it	Switch
Until	limit	SI	witch

Set the movement type of the up and down limit switches in revision.

Until Limit switch	When limit switches are enabled the elevator will stop before reaching its floor.
Until Floor	Even when limit switches are enabled the elevator will go to its floor.

DIGITAL SETTING

When the floor number is blinking, set the floor number with the UP-DOWN buttons till you come to the floor number you want to change. Press the ENTER button and next you will see the digits blinking. Set the value you like. When finished exit with the exit button. Or if you want to set another stop/floor, press the enter button, when floor number is blinking, repeat the steps.

Indicator type	Outputs that can be selected
7 Segment indicator	-4, -3, -2, -1, 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10 A, B, C, D, E, F, H, J, L, N, O, P

	DISPLAY OUTPUT
16:Display Output Normal	Set the display output of the HD EK0-10 controller card and HD EK0 SERI card.
7 Segment output	Normal output.

7 Segment butput	Normat output.
Gray code output	Gray code output.

MAX. CALL REGISTRATION

17:Max. Call Re9. 010	Set the maximum amount of calls that can be registered from within cabin. When this number is reached it stops registering any calls from within cabine.	
01 - 10	Set the number of stops between the minimum and maximum.	
	NUMBER OF BASEMENT	
18:Number of basement 000	Set the number of basement here.	



If the elevator is down collective, the floors that are under the basement that is set, it will be up collective. Note: Used in command types except for down collective.

19:Fire Stop 01	Set here the fire stop. When Fire input (at YAN) is active the elevator goes to the defined floor directly and waits with its doors open. Ele- vator will return to normal operation mode when fire signal is over		
01 - 10 Seconds This is the minimum and maximum time that is waited before park stop.			
Cancel	Fire stop is not defined in the system.		
	PARK STOP		
20:Park stop 05	Set the park stop here. When elevator pauses its operation,it goes to this floor and waits with open doors.		
	RETURN TO PARK		
21:Return to Park 200 Seconds	Set the waiting time before going to park stop.		
0 - 250 Seconds	Set the waiting time between the minimum and maximum.		
BUSY TIME			
22:Busy Time 006 Seconds	Set the cabin light delay here.		
5 - 20 Seconds	Set the cabin light delay time between the minimum and maximum.		
•			

FIRE STOP

According to the EN 81-1/2 standarts it is not allowed to bypass the cabin light delay.

On elevators with simple command (non-collective) this parameter must me equal to the "WAIT AT STOP" time. And the busy time must be at least 2 seconds.

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WAIT AT STOP			
23:Waiting Time at Floor 008 Seconds	Set the waiting time before going to other registrations while col- lecting.		
3 - 15 Seconds	Set the waiting time at floor between the minimum and maximum		
According to the EN81-1 and EN81-2 of al least 2 seconds when moving a	2 standarts, elevators with manual doors must have a waiting time Igain after reaching its floor		
On elevators with simple command LIGHT" time and must be at least 2 s	(non-collective) this parameter must me equal to the "CABIN seconds.		
	OPEN DOOR TIME		
24:Open Door Time 15 Seconds	Set the time from opening till closing of the automatic door.		
05 – 20 Seconds	Set the door open-close time between the minimum and maximum.		
	LOCK WAITING TIME		
25:Lock waitin9 008 Seconds	Set the maximum time to wait for the door lock signal (140) after getting the door closed signal.		
8 - 30 Seconds	Set the lock waiting time between the minimum and maximum.		
	DOOR STILL OPEN ERROR		
26: Door Still Open Error 015 Seconds	If after the time set in this parameter the door is not closed yet the control panel will go out of service. It is possible to choose to bypass this function.		
0 - 250 Seconds	Set the time for passing the door still open error between the minimum and maximum.		

	FOTOSEL BEKLEME SÜRESİ		
27: Photocell Waiting time 003 Seconds Seconds Seconds			
02 – 05 Seconds Set the photocell waiting time between the minimum and maximum			
	FAST CRUISING		
28: Fast Cruisin9 015 Seconds	Set the maximum time of cruising between 2 stops. If this time should be exceeded, the system automatically stops the movement of the cabin and blocks it.		
0 - 100 Seconds	Set the fast cruising time between the minimum and maximum.		
According to the EN81-1 / 2 standards following:	s motor operation time work must not exceed the smaller of the		
o 45 seconds o Longest cruising distance +10 seconds o If longest cruising distance is less than 10 seconds, the timeout should be at least 20 seconds			
SLOW CRUISING			
29: Slow Cruisin9 015 Seconds	Set the maximum time of slow cruising from the moment it meets the stopper of the target floor. If this time should be exceeded, the system automatically stops the movement of the cabin and blocks it.		
29: Slow Cruisin9 015 Seconds 0-100 Seconds	Set the maximum time of slow cruising from the moment it meets the stopper of the target floor. If this time should be exceeded, the system automatically stops the movement of the cabin and blocks it. Set the slow cruising time between the minimum and maximum.		
29: Slow Cruisin9 015 Seconds 0-100 Seconds	Set the maximum time of slow cruising from the moment it meets the stopper of the target floor. If this time should be exceeded, the system automatically stops the movement of the cabin and blocks it. Set the slow cruising time between the minimum and maximum. RP DELAY		
29: Slow Cruisin9 015 Seconds 0-100 Seconds 30:RP Delay 02600	Set the maximum time of slow cruising from the moment it meets the stopper of the target floor. If this time should be exceeded, the system automatically stops the movement of the cabin and blocks it. Set the slow cruising time between the minimum and maximum. RP DELAY It could be demanded with roped VVVF systems to delay the fall of the main contactor. In such cases, the RP delay of the relay output is set by this parameter.		
29: Slow Cruisin9 015 Seconds 0 - 100 Seconds 30: RP Delay 02600 0000 - 25000 Miliseconds	Set the maximum time of slow cruising from the moment it meets the stopper of the target floor. If this time should be exceeded, the system automatically stops the movement of the cabin and blocks it. Set the slow cruising time between the minimum and maximum. RP DELAY It could be demanded with roped VVVF systems to delay the fall of the main contactor. In such cases, the RP delay of the relay output is set by this parameter. Set the contactor delay time between the minimum and maximum		
29: Slow Cruisin9 015 Seconds 0 - 100 Seconds 30: RP Delay 02600 0000 - 25000 Miliseconds	Set the maximum time of slow cruising from the moment it meets the stopper of the target floor. If this time should be exceeded, the system automatically stops the movement of the cabin and blocks it. Set the slow cruising time between the minimum and maximum. RP DELAY It could be demanded with roped VVVF systems to delay the fall of the main contactor. In such cases, the RP delay of the relay output is set by this parameter. Set the contactor delay time between the minimum and maximum		
29: Slow Cruisin9 015 Seconds 0 - 100 Seconds 30: RP Delay 02600 0000 - 25000 Miliseconds 31: Plu9 delay 00600	Set the maximum time of slow cruising from the moment it meets the stopper of the target floor. If this time should be exceeded, the system automatically stops the movement of the cabin and blocks it. Set the slow cruising time between the minimum and maximum. RP DELAY It could be demanded with roped VVVF systems to delay the fall of the main contactor. In such cases, the RP delay of the relay output is set by this parameter. Set the contactor delay time between the minimum and maximum PLUG DELAY Set here the waiting time after the 130 circuit.		

LOCK DELAY			
32: Lock Delay 00100 Miliseconds	Set the maximum waiting time for arrival of the lock (140) signal after the door closed signal.		
0 - 2000 Miliseconds	Set the lock delay time between the minimum and maximum.		
	MAINTENANCE TIME		
33: Maintenance Time 32 Days	For every day the card operates the value of this parameter drops by one. For example, if it is set for 45 days, this parameter will Show a value of 15 when 30 days have passed. After 45 days the value will be 0.		
45-250 Days	Set the maintenance time between the minumum and maximum.		
	CHANGE PASSWORD CODE		
34:Chan9e Password	Set or change the password code here.		
1_0_0_0	If the display looks like this, the password is activated.		
	COUNTER TYPE		
35:Counter Type MØ	Set here your selection of the elevator floor sensor.		
Standart M0	Standard M0 counter.		
Standart M1	Standard M1 counter.		
	FACTORY SETTINGS		
36:Factory Settings	Here you can cancel your settings and return to factory settings.		

HD Eko 10 Control Card Key Names

Кеу	Description			
R				
S	Main Supply			
MP	Mains Neutral			
1	Cabine Feed input			
2	Cabine Light Feed			
K3	Door Close Signal			
K5	Door Open Signal			
K15	Common signal of door open and door close			
KN	Safety Circuit Neutral			
120	Stop Circuit	•		
130	Door Plug Contact Circuit Maks. 230Vac			
140	Door Lock Circuit			
M0	Floor counter magnetic switch input			
142	142 Signal			
KBL	Feedback Input of the main contactor. The normally closed contacts of the 100 signal o			
	the main contactor must be connected serially to this entry			
S1A-S1B	Cabin Serial Communication Terminals (With HD EKO SERIAL cards)			
100	Control Circuits Feed (+24Vdc)			
1000	Control Circuits Feed (OV)			
PTC	As long as there is motor thermistor ${\mathfrak G}$ panel thermostat sig	gnal		

HD Eko 10 Card Relay Outputs

Кеу	Description
11	Common RU1, RU2, RH, RF Contactors Feed Voltage
RU2	Up Direction Contactor
RU1	Down Direction Contactor
RH	High Speed Contactor
RF	Low Speed Contactor

HD Eko 10 Jumper Connection

3-jumper connection on the HD Eko 10 Card		
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↓ ↓ ↓	● +	
If 31, 32, 02 and 12 signal outputs are 100	If 31, 32, 02 ve 12 signal outputs are 1000	

HD KLS Card Key Names

Кеу	Description
869	Revision Key (from the Revision Box)
500	Revision Downward Button
501	Revision Upward Button
FRI	Fire Alarm Contact
DEP	Earthquake Alarm Contact
DTS	Door Close Button
K20	Door Open Button & Door Jam & Photocell Contact
804	Overload Contact
817	Down Obligatory limit Magnetic Switch
818	Up Obligatory limit Magnetic Switch
869P	Revision Key (to Controller Card)
2G	7-Segment Indicator Outputs
190	Common Simple Command Output
X1-X10	In/Out Controller Recorder Inputs
31	Downward Arrow Light
32	Upward Arrow Light
2	Out of Service Lights
12	Busy Lights

Magnetic Switch and Magnets SETUP

Standard MO counter system: Used in double speeds elevators where the declaration distance is smaller then half of the distance between two floors.

Drive Type	Cabin Position- ing Sensor	Early Door Opener Levelling	Magnetic Switch	Magnet
Double Speed	Standard MO Counter	Not applicable	M0 (Bi-stable)	Round Magnet

M0 Counter System SETUP

On MO counter system the cabin movement and floor information is detected with 2 types of magnetic Switches.

• Floor counter and decelerating magnetic switch (SMO, Bi-stable)

• Floor stopper magnetic switch (SJF, Bi-stable) On this counter system bi-stable magnetic switches and round magnets are used. M0 is used as the floor counter and also as the deceler ator. JF (142) switch works as the floor stopper.

- For the magnet arrangement please consult the connections diagrams.
- Connect the switch ends of the M0-100 and 142-100 terminals respectively.



An elevator (an elevator with safety measures such as an overload system and with automatic doors according to the standards) is risk free for its user and it falls upon elevator industrial companies like us and companies that take care of the installation and maintenance like yours to reduce any chance of risk of an accident to remissible levels. In the following some basic safety points are discussed in relation to the elevator control system. Please pay attention to all these measures to safely operate our lifts, and hence minimizing any risk of an accident. In order for the lift system to be according to the EN 81-1 / 2 standard, the control card, the control panel and electrical connections must be appropriately done. HEDEFSAN guarantees the compliance of the control card to the standards. But the control panel internal connections, external connections and other electrical connections are the responsibility of the installer. Do not pass the safety circuit in any way through a relay or contact. Hide the connectors of the plug and lock circuits connections in the door's free space in a way that it won't touch the door chassis. Take into account that water can flow from upper floors when the stairway is being cleaned and that also there could be liquid spillage inside the cabin. Therefore if possible the safety connections should be put into isolated boxes. If this it not possible they must be insulated with insulation tape. Door frames must be bounded to the grounding bus bar of the panel. When the grounding is not done, it is possible that the saftey circuit is bypassed through the door frame. Years of operation, dust, dirt, oil may cause the loss of functionality of the safety circuit. Do not forget to check the plug and lock functions on the periodic maintenance. HD Eko 10 safety circuit operates with 220Vac voltage. The motor contactors are fed directly from the safety circuit. In this way it prevents involuntary movements outside the control of safety circuits.



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